



Introduction

- **Learning mixture models** – fundamental problem in statistics and machine learning.
- **Applications** – density estimation and clustering.

- A PDF is a mixture of R component distributions if it can be expressed as a weighted sum of R multivariate distributions:

$$f_{\mathcal{X}}(x_1, \dots, x_N) = \sum_{r=1}^R w_r f_{\mathcal{X}|H}(x_1, \dots, x_N|r)$$

- When each conditional PDF factors into the product of its marginal densities we have:

$$f_{\mathcal{X}}(x_1, \dots, x_N) = \sum_{r=1}^R w_r \prod_{n=1}^N f_{X_n|H}(x_n|r)$$

- Common assumption: parametric form of the conditional PDFs such as Gaussian distributions.
- Most popular algorithm: Expectation Maximization [Dempster et al., 1977].
- Is it possible to recover mixtures of *non-parametric* product distributions?

Canonical Polyadic Decomposition

- An N -way tensor $\underline{\mathbf{X}} \in \mathbb{R}^{I_1 \times I_2 \times \dots \times I_N}$ is a multidimensional array. A polyadic decomposition expresses the tensor as a sum of rank-1 terms:

$$\underline{\mathbf{X}} = \sum_{r=1}^R \mathbf{A}_1[:, r] \circ \mathbf{A}_2[:, r] \circ \dots \circ \mathbf{A}_N[:, r]$$

- If the number of rank-1 terms is minimal, then the decomposition is called the CPD of $\underline{\mathbf{X}}$ and R is called the rank of $\underline{\mathbf{X}}$.

- Without loss of generality, we can restrict the columns of $\{\mathbf{A}_n\}_{n=1}^N$ to have unit norm and have the following equivalent expression:

$$\underline{\mathbf{X}} = \sum_{r=1}^R \lambda[r] \mathbf{A}_1[:, r] \circ \mathbf{A}_2[:, r] \circ \dots \circ \mathbf{A}_N[:, r]$$

Related Work

- **EM-based:**
 - parametric models (Gaussian, Exponential, Laplace, Poisson).
 - non-parametric models [Benaglia et al., 2009, Levine et al., 2011].
 - Kernel-based methods.
 - Lack Identifiability.
- **Tensor-based:**
 - GMMs [Hsu and Kakade, 2013], categorical [Jain and Oh, 2014].
 - Parametric models, algebraic algorithms \rightarrow EM for refinement.
- Identifiability for non-parametric mixtures of product distributions [Allman et al., 2009].
 - Identifiability of the conditional PDFs given the true joint PDF, if the conditional PDFs are linearly independent.
 - No estimation procedure.

Approach

- Discretization of each random variable by partitioning its support into uniform intervals $\{\Delta_n^i = (d_n^{i-1}, d_n^i)\}_{1 \leq i \leq I}$.
- Define the probability tensor (histogram):

$$\underline{\mathbf{X}}[i_1, \dots, i_N] = \Pr(X_1 \in \Delta_n^{i_1}, \dots, X_N \in \Delta_n^{i_N})$$

given by

$$\begin{aligned} \underline{\mathbf{X}}[i_1, \dots, i_N] &= \sum_{r=1}^R w_r \prod_{n=1}^N \int_{\Delta_n^{i_n}} f_{X_n|H}(x_n|r) dx_n \\ &= \sum_{r=1}^R w_r \prod_{n=1}^N \Pr(X_n \in \Delta_n^{i_n} | H = r). \end{aligned}$$

- Is it possible to learn the mixing weights and discretized conditional PDFs from missing/limited data? **Yes!** Joint factorization of histogram estimates of lower-dimensional PDFs.
- Is it possible to recover non-parametric conditional PDFs from their discretized counterparts? **Yes**, if the conditional PDFs are smooth!

Identifiability using Lower-dimensional Statistics

- Realizations of subsets of only three random variables are sufficient to recover $\Pr(X_n \in \Delta_n^{i_n} | H = r)$ and $\{w_r\}_{r=1}^R$.
- A histogram of any subset of three random variables X_j, X_k, X_ℓ can be written as

$$\underline{\mathbf{X}}_{j k \ell}[i_j, i_k, i_\ell] = \sum_{r=1}^R \lambda[r] \mathbf{A}_j[i_j, r] \mathbf{A}_k[i_k, r] \mathbf{A}_\ell[i_\ell, r]$$

which is a CPD of rank R .

- The parameters of the CPD are generically unique for $R \leq \frac{(\lfloor \frac{N}{3} \rfloor + 1)^2}{16}$.

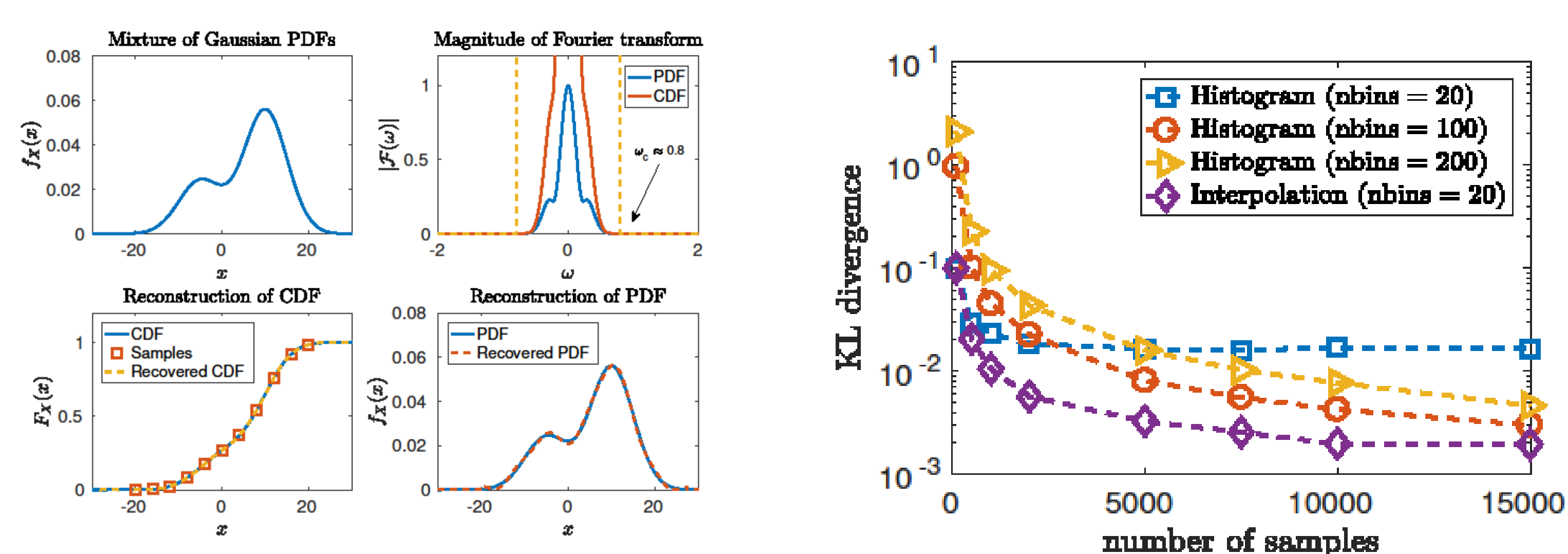
Remarks:

1. Finer discretization can lead to improved identifiability results. Many samples to reliably estimate these histograms!
2. Histograms of subsets of two variables correspond to Non-negative Matrix Factorization which is not identifiable in general!

Recovery of the Conditional PDFs

- **Proposition:** A PDF that is (approximately) band-limited with cutoff frequency ω_c can be recovered from uniform samples of the associated CDF taken π/ω_c apart.

Toy Example



Algorithm

- **Optimization problem:**

$$\begin{aligned} \min_{\{\mathbf{A}_n\}_{n=1}^N, \lambda} & \sum_{j=1}^N \sum_{k>j}^N \sum_{\ell>k}^N D(\hat{\underline{\mathbf{X}}}_{j k \ell}, [\lambda, \mathbf{A}_j, \mathbf{A}_k, \mathbf{A}_\ell]_R) \\ \text{s.t.} & \lambda \geq \mathbf{0}, \mathbf{1}^T \lambda = 1 \\ & \mathbf{A}_n \geq \mathbf{0}, n = 1, \dots, N \\ & \mathbf{1}^T \mathbf{A}_n = \mathbf{1}^T, n = 1, \dots, N \end{aligned}$$

- **Alternating optimization approach:**

Cyclically update the variables while keeping all but one fixed.

$$\min_{\mathbf{A}_j \in \mathcal{C}} \sum_{\substack{k \neq j \\ l \neq j \\ l > k}} D(\underline{\mathbf{X}}_{j k \ell}^{(1)}, (\mathbf{A}_\ell \odot \mathbf{A}_k) \text{diag}(\lambda) \mathbf{A}_j^T)$$

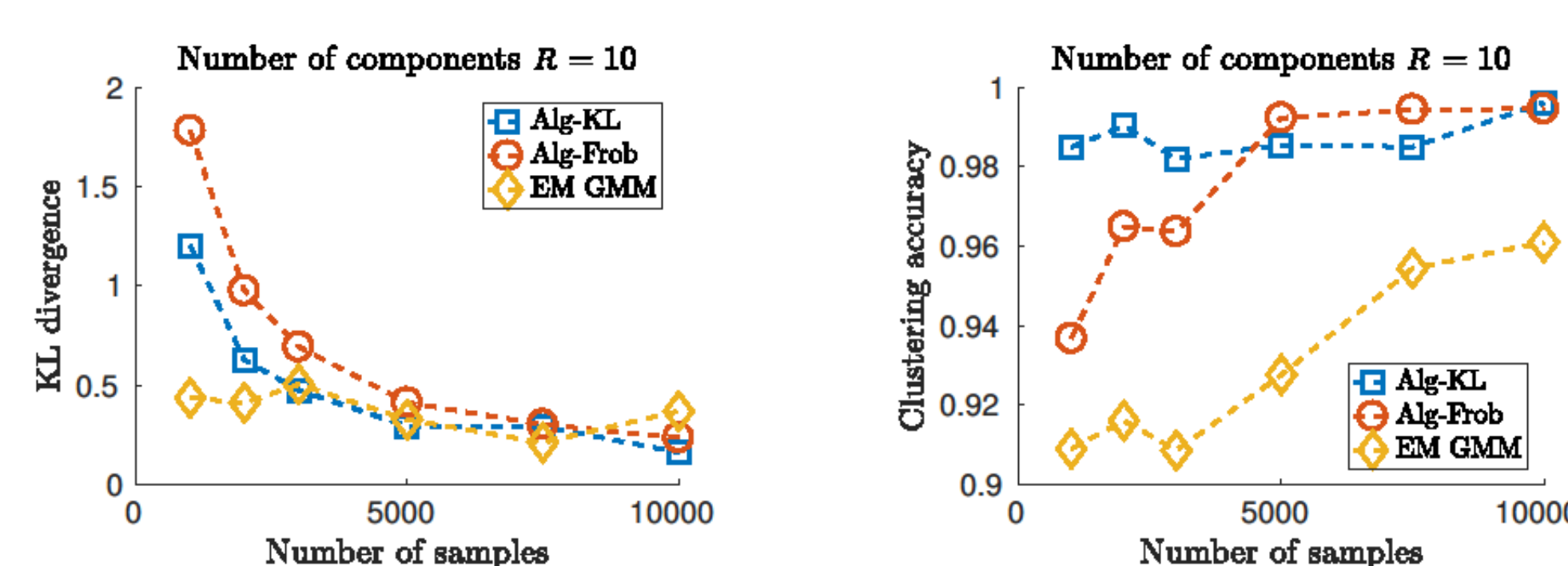
solved via Exponentiated Gradient. The update rule becomes:

$$\mathbf{A}_j^\tau = \mathbf{A}_j^{\tau-1} \otimes \exp(-\eta_\tau \nabla f(\mathbf{A}_j^{\tau-1}))$$

Similarly for λ .

Experiments

- **Conditional PDFs: Gaussian**



- **Conditional PDFs: Gamma**

